Scientific report for the NERC Geophysical Equipment Facility Loan 977: "A Study of the Hazard and Geomorphic Change Caused by Debris Flows in Iceland" PI: M. R. Balme Report compiled by S. J. Conway Users: S. J. Conway A. M. Barrett, P. Fawdon, J. D. Ramsdale

Abstract

This loan formed an additional aspect to a European Facility for Airborne Research (EUFAR) funded project entitled "A Study of the Hazard and Geomorphic Change Caused by Debris Flows in Iceland". This EUFAR project included the acquisition of LiDAR (airborne laser altimeter) and air photography by the NERC ARSF (EUFAR12_02). Four differential GPS were used by two different field teams to provide support for a NERC ARSF deployment on 27 August 2012 and over an additional week to make GPS measurements for qualitycheck and georeferencing purposes. These data collection activities were successful and although weather conditions prevented the key site from being surveyed, aerial data were collected elsewhere that enabled the support of a number of different projects being pursued by the project team-members. The LiDAR and air photo datasets are being used actively by the project teams to support three themes of research: 1) paraglacial slope adjustment in Iceland led by J. Coquin supervised by team member A. Decaulne, 2) a PhD project by A.M. Barratt under the supervision of team member M.R. Balme concerning periglacial landforms and 3) as an analogue for investigations into martian surface processes lead by S.J. Conway. Because airborne LiDAR data could not be collected near Ísafjörður we performed GPS surveys over two new debris flows to contribute to the initial project aims and to the monitoring dataset are building on the debris flows in this area. These data will be used in a new PhD project concerning mass flows in Iceland, to start in October 2014.

1. Background

One of the main risks to population in Iceland, particularly in the fjords, is the action of debris flows. These are mixtures of boulders, sediment and water that surge downslope after prolonged/intense rainfall or sudden snowmelt (Decaulne et al., Geogr. Ann. Ser. A-Phys. Geogr.2005). Metre-size boulders can be carried in debris flows causing damage to property and, in some cases, loss of life. To better understand the risk posed by these flows, both the physics of their motion and the role of the geological setting in initiating slope instability need to be understood. We initially proposed to collect high resolution topographic data in Súgandafjörður and Skutulsfjörður, which were previously surveyed by NERC ARSF in 2007, and from the slopes of western Skagafjörður (Tindastóll).

Unfortunately, due to poor weather conditions, the sites in Súgandafjörður and Skutulsfjörður were not surveyed and an additional site at Deildardalur was surveyed instead (Fig. 1). These sites were key to pursuing the theme of debris flow research as outlined in the original EUFAR proposal and this line of research was put on hold until collection of these key data occurred in summer 2013. This project now forms part of a PhD project starting in October 2014 under the supervision of some of the EUFAR team members. Some GPS survey data were obtained as part of this loan to partially compensate for the lack of LiDAR survey and these will be used as part of this PhD project.

Although the initial aims of the project could not be completed these data have been used for three other projects with details in the following sections.

1.1 Paraglacial slope adjustment

The Skagafjörður region is comprised of layered basaltic bedrock forming plateaus that are dissected by glacial valleys. This region has been ice-free since the early Holocene and post-glacial processes are thought to have contributed to the slope instability of this area, with >130 landslides mapped in this area (Pétursson, Skagfirsk náttúra 2008). Paragalcial landforms such as landslides and rock slope failures have been studied in this region, but little attention has been paid to deep-seated gravitational slope deformation – so called "sackung". Such features are found at the crests of the Óslandshliðarfjöll Mountain within the Deildardalur site and the LiDAR data and aerial photo mosaic have enabled detailed study of these features by PhD student J. Coquin under the supervision of team member A. Decaulne.

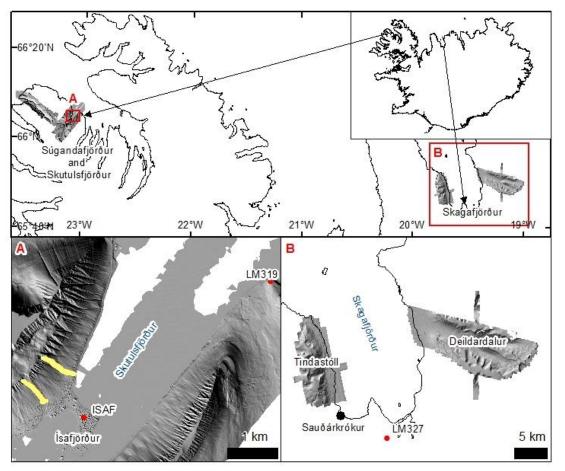


Figure 1:Maps showing the location of the sites studied in Iceland and some of the GPS data collected. The hillshaded relief map of Ísafjörður is from the NERC ARSF 2007 LiDAR survey and the hillshaded relief maps of Tindastóll and Deildardalur are from the NERC ARSF 2012 LiDAR surveys. A) Detailed view of the Ísafjörður site with the additional GPS survey points shown in Fig.2in yellow and in red the location of the pillar (LM319) and permanent recording station (ISAF) that would have been used for the abandoned aerial survey. B) Detailed view of the Skagafjörður site, the Tindastoll site was flown as planned and the Deildardalur site was flown as a replacement for Ísafjörður. In red the location of the pillar LM327 used as a base station location for the GPS used to correct the LiDAR data.

1.2 Periglacial processes

The repeated freezing and thawing of the permafrost active layer in periglacial environments can result in the sorting of mixed soils into domains of fine particles surrounded by circles or lines of larger stones. Active

sorted stone circles are found on top of Tindastóll mountain, with relic features in other parts of the Skagafjörður area (Feuillet *et al.,* Geomorphology 2012). The sorting process itself is poorly understood and the PhD project of A. M. Barrett, supervised by team member M. R. Balme, aims to 1) determine the extent to which sorted circle morphology is controlled by topographic factors as predicted by the models of Kessler and Werner (Science, 2003) and 2) to determine if the sorted forms that we have observed on Mars are also controlled in the same way.

1.3 Martian analogue studies

Martian gullies are kilometre-scale landforms that strongly resemble gullies formed by water-driven processes on Earth; however we know that they formed within the last few million years when the climate has been too dry and cold to support the production of liquid water at the surface. Martian gullies can be visually similar to gullies carved by debris flows in Iceland. We have used hydrological analysis techniques on high resolution elevation models (from LiDAR and stereo photogrammetry) to successfully demonstrate that gullies on Mars resemble Icelandic debris flow gullies in terms of their 3D attributes as well as visually (Conway *et al.*, Geol.Soc. Sp. Ed. 2011). Hence, we showed that water was recently active on Mars' surface and therefore Mars must have undergone dramatic changes in climate during this time. In Conway *et al.*, (Geol.Soc. Sp. Ed. 2011) we used the LiDAR data of Ísafjörður area from 2007. The data from 2012 will build on this existing analogue dataset and allow further comparison of martian gullies with debris flows with different configurations and settings compared to those near Ísafjörður.

2. Survey procedure

To directly support the ARSF surveys we set up the differential GPS on survey pillars with known positions at Sauðárkrókur and Ísafjörður (Fig. 1; LM327 and 319). The tribrachs were directly screwed onto the pillars and the distance from the antennae's reference plane to the reference plates on the pillars were measured. The GPS were deployed 1.5 hours prior to the planned survey at 1s recording rate and taken down once confirmation of the survey being completed was received. A backup station was set up nearby on a tripod, in case the GPS on the pillar failed.

In order to collect some ground control data to assist in quality control and processing of the aerial LiDAR data we collected additional GPS data using a rover-base station pair. We collected data along roads and around other objects visible from the air (building footprints, abandoned tractor tyres, etc). Firstly we set up a local base station, which we ran simultaneously with another GPS setup on the known-pillar position, to tie it in to the same frame of reference as the aerial survey. Then, while maintaining this local base station, we operated one or two rovers, collecting 5-10 epochs of data at each survey point.

Lastly we collected data over the deposits of two debris flow that occurred since the 2007 LiDAR survey in Ísafjörður to partly compensate for the lack of repeat LiDAR collection. A similar approach was used to that outlined above for the quality control data. After successful testing we surveyed on one day using the permanently recording GPS in Ísafjörður (ISAF) as the base station, enabling us to use two rovers.

3. Data quality

Pillar LM327 was occupied for 9h 56' between the hours of 08:37 and 18:33 on 27th August and a position quality of better than 1cm was reported in all orientations. The western Skagafjörður site was flown

between 10:05 and 11:04 and the Deildardalur site between 13:35 and 15:52. Static GPS data for Ísafjörður was not used as this site was not flown. The backup station's data were not required.

In total 2344 datapoints were collected for quality control and GPS survey purposes. These points had an average vertical error of < 9cm for surveys on rough terrain and < 3cm for control point surveys. The horizontal error was always < 3cm. A summary of the errors is given in Table 1. The maximum value of the errors are within the expected range for errors introduced by terrain roughness and user point-positioning, hence are within acceptable bounds for this kind of data collection.

Date	ID	Site	Oper -ator(s)	Height - Z (m)			Horizontal – X (m)			Horizontal – Y (m)			Count
			-ator (5)	Mean	Min	Max	Mean	Min	Max	Mean	Min	Max	
23/08/2012	Road control	Sauðárkrókur	JDR/SJC	0.0057	0.0000	0.023	0.0027	0.0000	0.0095	0.0001	0.011	0.031	96
26/08/2012	Ditch control	Ísafjörður	JDR	0.0021	0.0000	0.011	0.0012	0.0000	0.008	0.0035	0.0000	0.016	312
26/08/2012	Small DF	Ísafjörður	JDR	0.0021	0.0000	0.012	0.0023	0.0000	0.010	0.0058	0.0000	0.032	265
27/08/2012	Road Control	Ísafjörður	JDR	0.0053	0.0002	0.014	0.0021	0.0001	0.010	0.0053	0.0002	0.014	80
28/08/2012	Large DF	Ísafjörður	JDR/SJC	0.0032	0.0011	0.037	0.0019	0.0007	0.025	0.0062	0.002	0.090	944
29/08/2012	Large DF	Ísafjörður	JDR	0.0034	0.0012	0.015	0.0021	0.0008	0.0084	0.0065	0.0021	0.025	545
29/08/2012	Ski slope control	Sauðárkrókur	AMB/PF	0.0023	0.0007	0.012	0.0016	0.0005	0.0094	0.0046	0.0015	0.022	102

Table 1: Summary of GPS data points collected with vertical and horizontal errors given as standard deviations.

4. Processing and modelling

The GPS data collected to support the ARSF survey were sent to the NERC ARSF Data Analysis Mode and they used them together with data from the aircraft's GPS and Inertial Measurement Unit (IMU) to produce a georeferenced pointcloud of LiDAR data and camera external orientation parameters for the aerial photographs. The LiDAR points were gridded at 1 m/pix using LasTools and the aerial photographs mosaiced using Agisoft PhotoScan with control points picked from the LiDAR data.

The quality control and survey GPS data were post-processed using the Leica GeoOffice Software and exported to an ArcGIS shapefile for further analysis. The quality control data were then passed directly to the NERC ARSF DAN for checking their LiDAR data processing.

	ARSF	GEF13	GEF15	GEF16	GEF20					
17 August 2012		transporte	d to Iceland							
18 August 2012										
19 August 2012										
20 August 2012				transporte	ed to Iceland					
21 August 2012		travel to Sauðárkrókur from Reykjavik								
22 August 2012		local base station	ARSF LM327 pillar base		local base station					
23 August 2012		Sauðárkrókur rover	local base station	Sauðárkrókur rover	local base station					
24 August 2012		travel to Ísafjörður	local base station	local base station	travel to Ísafjörður					
25 August 2012		local base station	ARSF LM327 pillar base	local base station	ARSF LM319 pillar base					
26 August 2012		Ísafjörður rover	local base station		ARSF LM319 pillar base					
27 August 2012		local base station + Ísafjörður rover	local base station	ARSF LM327 pillar base	ARSF LM319 pillar base					
28 August 2012		Ísafjörður rover	local base station	Sauðárkrókur rover	Ísafjörður rover					
29 August 2012					ARSF LM319 pillar base					
30 August 2012		travel back to Reykjavik from fieldsites								
31 August 2012		Returned from Iceland								

Table 2: Details of the instrument deployments.

5. Interpretation & Preliminary findings to date

5.1 Change caused by debris flows

By comparing the elevation values recorded in the GPS survey of two debris flows above Ísafjörður with the digital elevation model produced from the 2007 LiDAR data we were able to perform an initial analysis on the topographic change engendered by these flows (Fig. 2). Unexpectedly 2-3 m of deposition was recorded within the alcove of the large debris flow (as corroborated by visual observations), which we infer could engender future debris flows. Our intention is to bring together these observations with observations derived from the new ARSF LiDAR survey flown in 2013 to publish on the potential for future debris flow events in this region derived from mass movement into the alcoves.

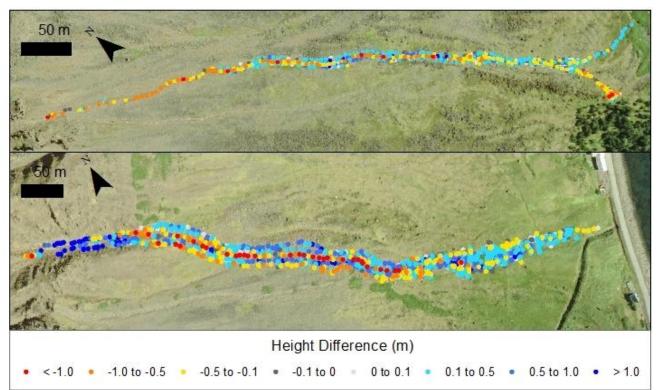


Figure 2: GPS points collected above Ísafjörður, with the colour indicating the difference between the height recoded by the LiDAR in 2007 and that recorded by the GPS survey in 2012. The small debris flow is shown at the top and the large debris flow at the bottom – in both cases deposition is recorded on the flanks and erosion down the channels. Aerial photos are from the 2007 NERC ARSF survey.

5.2 Paraglacial slope adjustment

J. Coquin and co-authors (Coquin *et al.*, Earth Science Reviews 2014) have identified and mapped (using the LiDAR, air photo and field measurements) three distinctive set of graben trending along a 12 km ridge section in the mountains in the Deildardalur site. From these data they suggest that these graben are caused by a sackung-style of gravitational spreading. They conclude that this deformation started before the ice was completely removed (during the early stage of the Late Weichselian deglaciation), rather than after its removal as is commonly believed. They surmised that the role of sackung in long term mountain denudation and land scape evolution under a paraglacial landscape system is more important than previously thought.

5.3 Periglacial processes

From field observations and by using the aerial photography from the NERC ASF survey A.M. Barrett recorded a range of types and scales of sorted patterned ground in the western Skagafjörður region (Fig. 3), which are similar to those he has observed in his martian datasets. Analysis is ongoing and he plans to integrate the topographic data with the image data in order to assess the topographic control of the forms in Skagafjörður and on Mars.



Figure 3: Left: metre scale Sorted patterned ground on top of Tindastóll. This circle is approximately 1.5 m across. Right: NERC ARSF aerial image of the summit of Tindastóll. From right to left, sorted circles can be seen to become elongated then transition into a series of stripes. Circles are 1-3 metres in diameter.

5.4 Martian analogue

We have used the western Skagafjörður LiDAR dataset and used it as a debris flow end-member in a study where we compare the 3D terrain attributes of martian gullies to dry lunar gullies and to wet terrestrial fluvial and debris flow gullies in order to ascertain the moistness of the martian gullies. We conclude that martian gullies are unlike dry lunar gullies and are intermediate between fluvial and debris flow gullies on Earth. This confirms the findings of our previous work where we concluded that water has been recently active on Mars' surface and therefore Mars must have undergone dramatic climate changes in the last few million years. This work is in preparation for publication and is funded by Leverhulme Trust grant number RPG-397. We plan to use these data in future to compare the 3D attributes of features that are interpreted to be solifluction lobes and rock glaciers on Mars to those found within the LiDAR surveys in Skagafjörður.

6. Conclusions and recommendations

The four NERC GEF GPS were used to fulfil the primary objective of supporting the EUFAR funded NERC ARSF flights in Iceland in 2012. They were also used to collect ground control data to assist in the quality control of the data by NERC ARSF DAN. As a result, correctly georeferenced aerial photo mosaics and digital elevation models were produced of the two survey sites, which although could not be used as intended for the initially proposed project (because the survey of the key site was abandoned due to weather constraints), have contributed to three other lines of research. The GPS were also used to collect additional data over two debris flows in Ísafjörður, which were not covered by the aerial survey as planned. These data will contribute

to the ongoing monitoring of debris flow activity in this area and will support a PhD project starting in October 2014.

7. Publications

Journal Publications

Julien Coquin, Denis Mercier, Olivier Bourgeois, Etienne Cossart & Armelle Decaulne (submitted).Mountain gravitational spreading coeval with Late Weichselian deglaciation: impact on glacial landscapes in Tröllaskagi, North Iceland. Earth Science Reviews.

Conference presentations

Julien Coquin, Denis Mercier, Olivier Bourgeois, Etienne Cossart & Armelle Decaulne, 2014. Morphologic evidence for a sackung event in Tröllaskagi mountain (Northern Iceland). 31st Nordic Geological Winter Meeting, Lund, Sweden, 7-11 january 2014.

Alex Barrett, Matthew Balme, Manish Patel, Axel Hagerman 2013 "The latitudinal distribution of putative periglacial landforms on the northern plains of Mars". EGU General Assembly.

Alex Barrett, Matthew Balme, Manish Patel, Axel Hagerman 2014 "Patterned ground as an indicator of periglacial activity in and around Lomonosov Crater, Mars". UK planetary Forum Early Careers Scientists Meeting.